

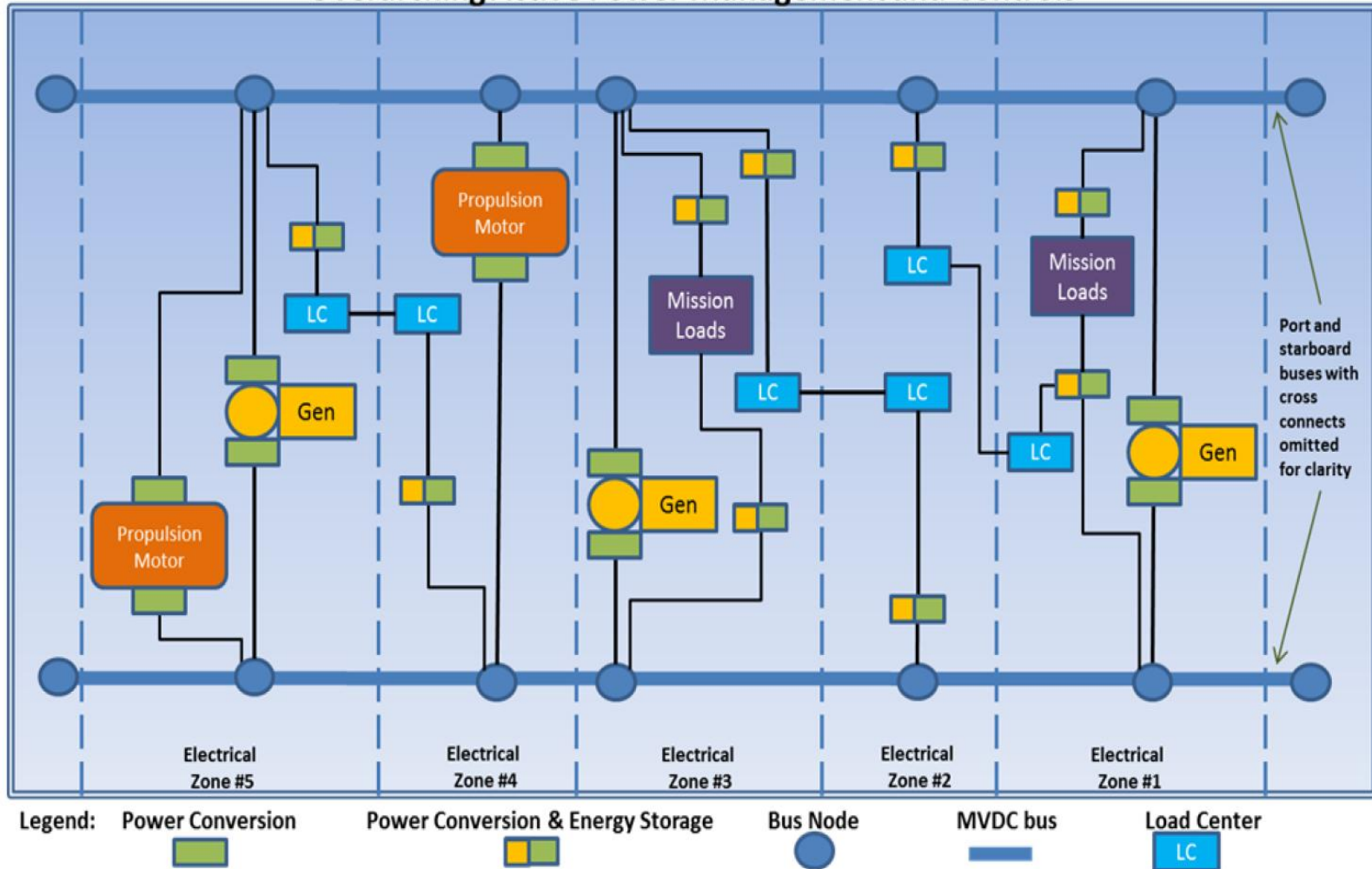
# MVDC Grounding and Common Mode Current Control

Dr. Norbert H. Doerry  
Dr. John V. Amy Jr.

IEEE Electric Ship Technologies Symposium (ESTS 2017)  
Arlington, VA  
August 15-17, 2017

# MVDC Reference Architecture

## Overarching Active Power Management and Controls

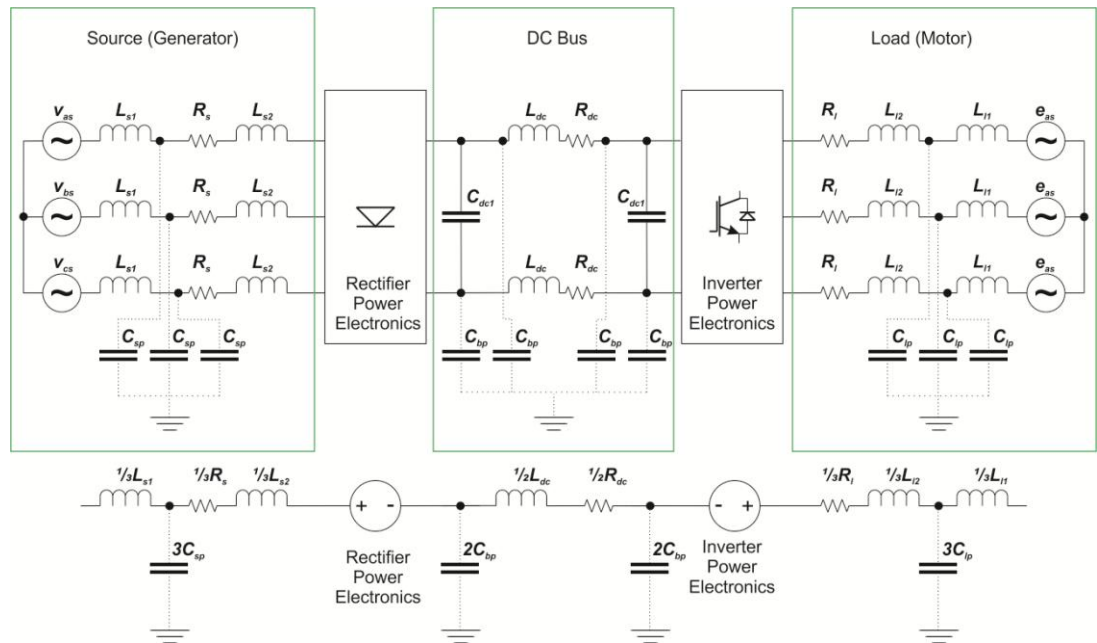
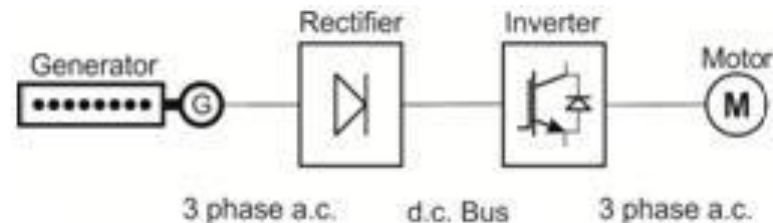


# Introduction to Common Mode

- Common mode currents are also called leakage current: the return path of common mode currents is typically through the ship's hull.
- Common mode currents flow through the hull due to a.c. voltages of a power systems neutral with respect to the hull potential interacting with parasitic capacitances.
  - The neutral voltage with respect to ground is the instantaneous average of all the power system conductor voltages with respect to ground.
- The difference in power system neutral voltages between the input and the output of a power electronics based converter is the dominant source of common mode current.
- Common mode impedances are a function of frequency.
- Common mode currents can result in safety hazards and corrosion.
- Common mode currents can be a source of Electromagnetic Interference (EMI)
- Common mode currents are impacted by the grounding method.

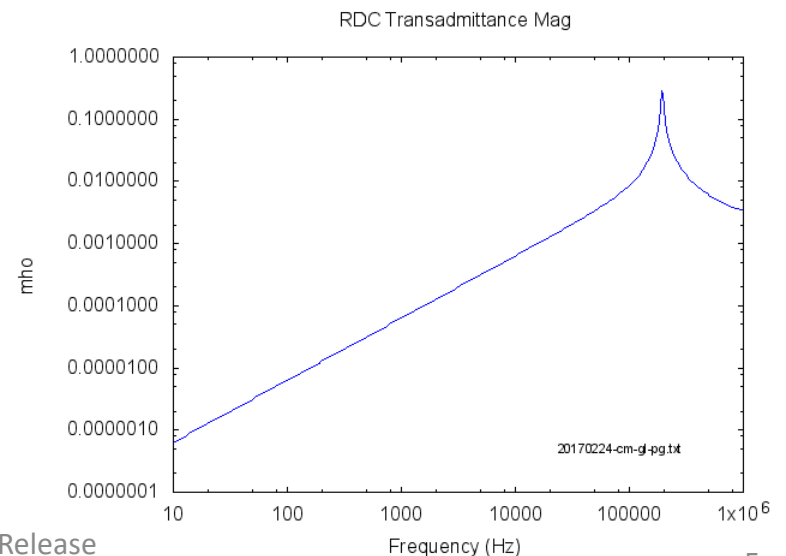
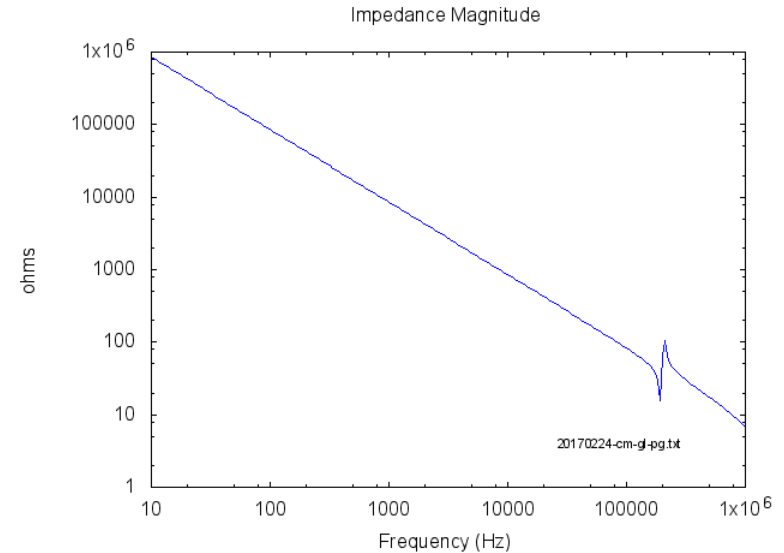
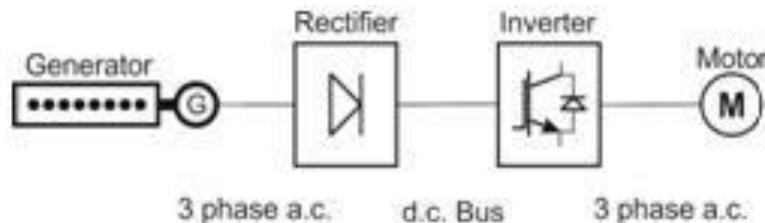
# Simplified Model

- Common Mode model derived from 3 phase model
- Eliminates components that only impact normal “Differential Mode”
- Combines paralleled components.
- Based on method described by Brovont and Pekarek presented at ESTS 2015

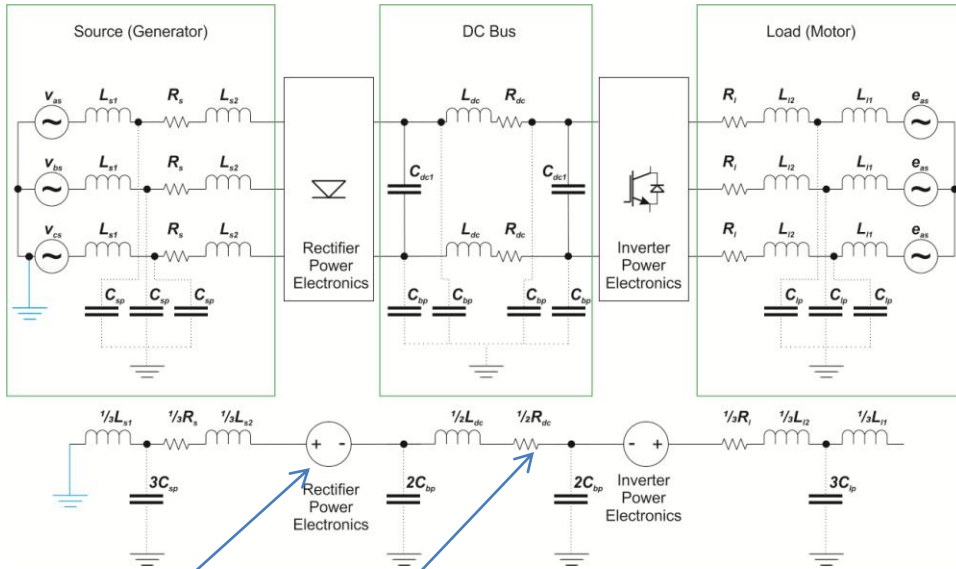


# Metrics of Interest

- Magnitude of common mode impedance seen by a common mode source as a function of frequency
  - Indicator of common mode currents local to equipment
- Magnitude of common mode “transadmittance” as a function of frequency
  - Ratio of common mode current in the distribution feeder (d.c. bus) to the common mode voltage
  - Measures how well common mode current is contained to the vicinity of the equipment.
- Design Objectives:
  - Prefer to have common mode currents depend on design variables and not hard to predict parasitic values
  - Minimizing transadmittance at frequencies of interest is of higher priority than maximizing common mode impedance
  - Need to keep common mode impedance high enough to limit common mode current local to the equipment.

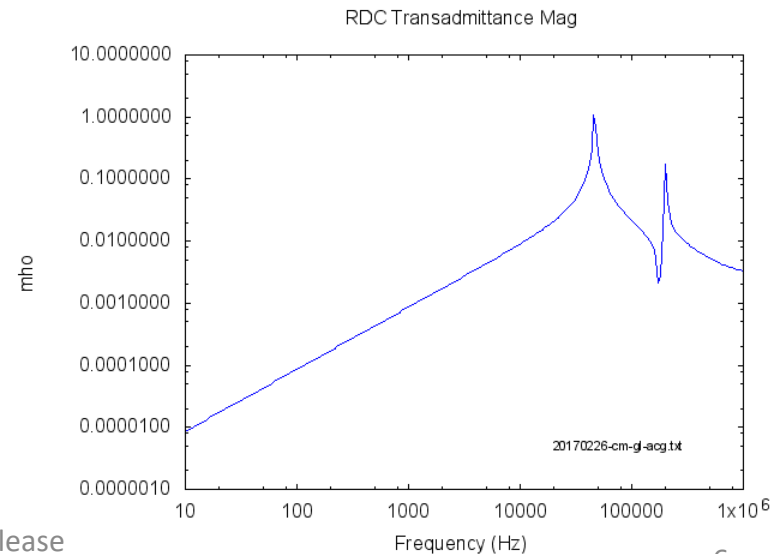
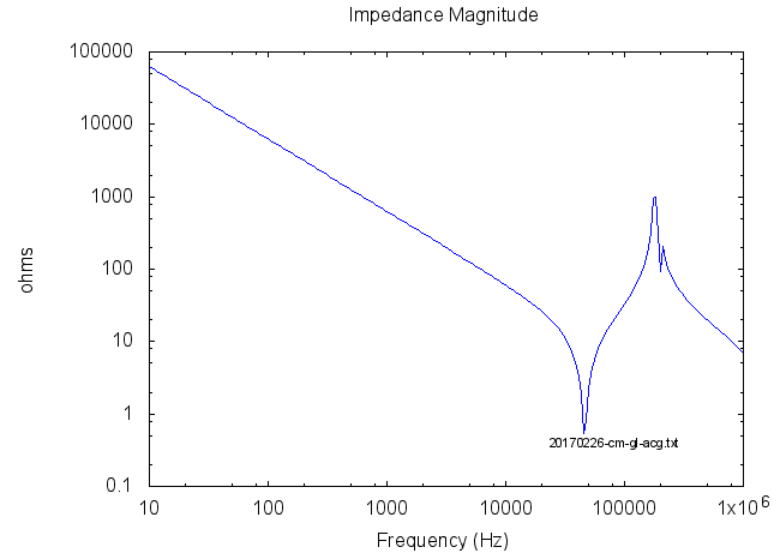


# A.C. Side Hard Grounding

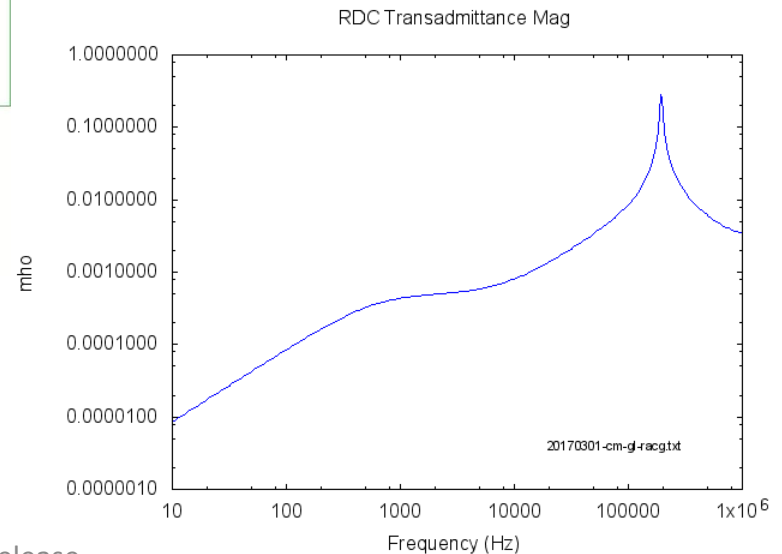
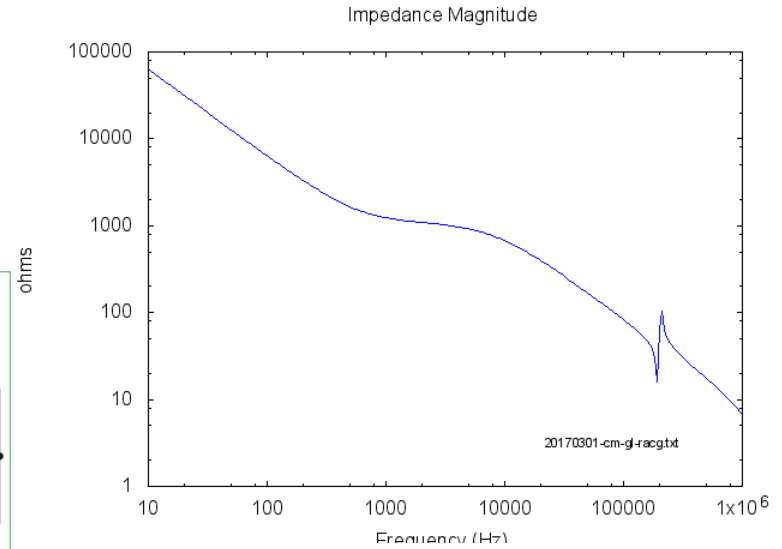
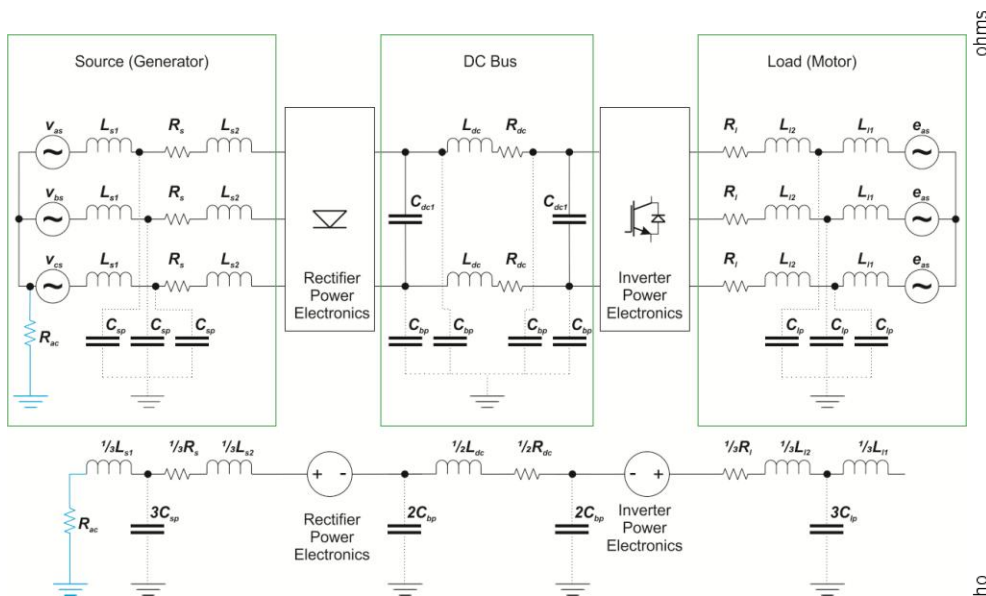


Impedance: common mode voltage associated with Rectifier Power Electronics divided by the common mode current through the Rectifier Power Electronics.

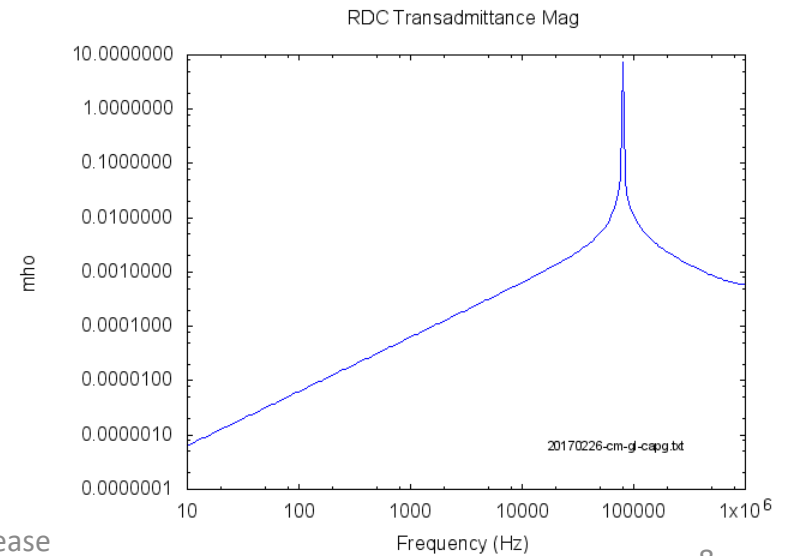
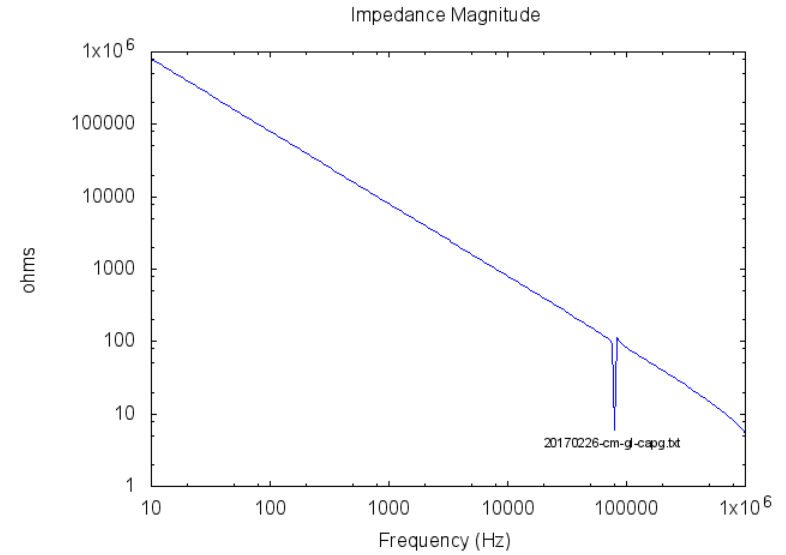
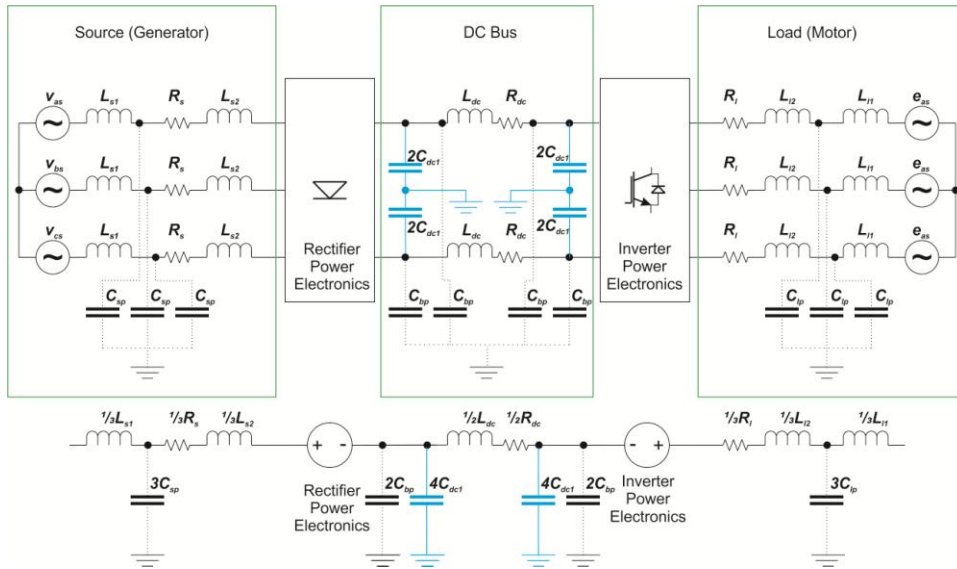
Transadmittance: common mode current through the DC bus divided by the common mode voltage associated with Rectifier Power Electronics.



# A.C. Side High Resistance Grounding

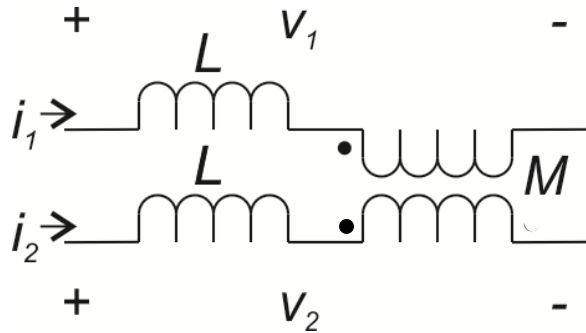


# D.C. Side shunt capacitors





# D.C. Side Choke



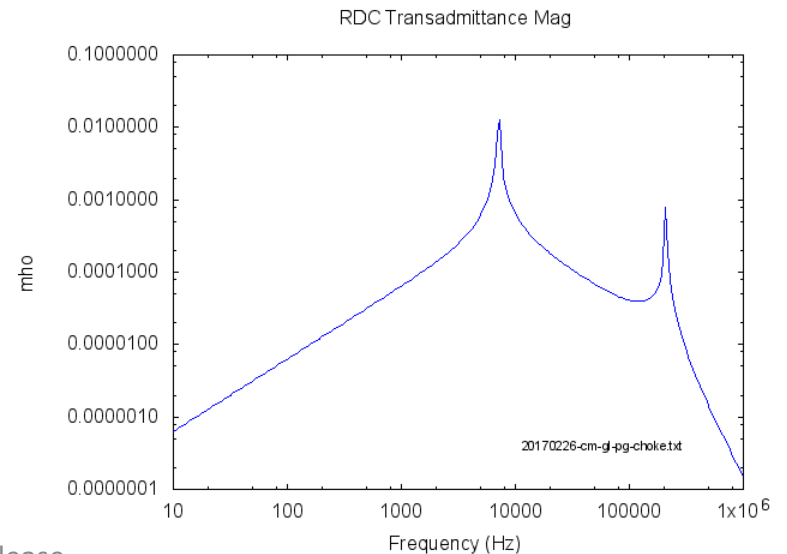
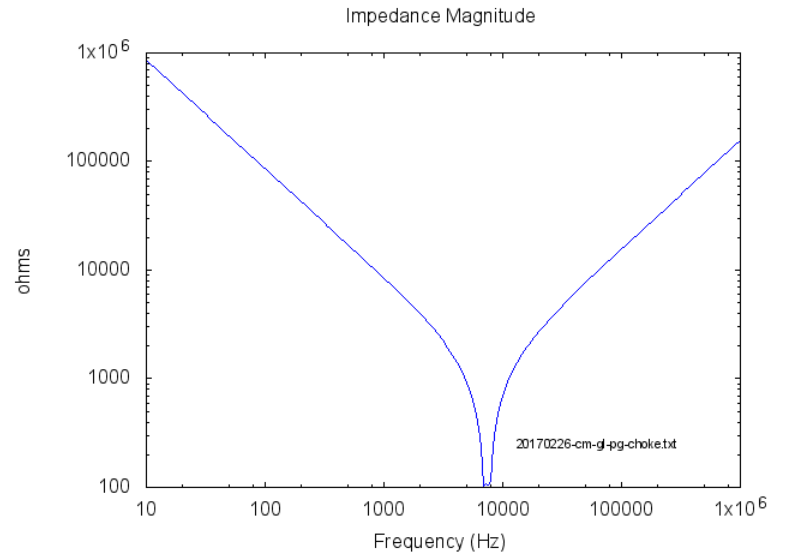
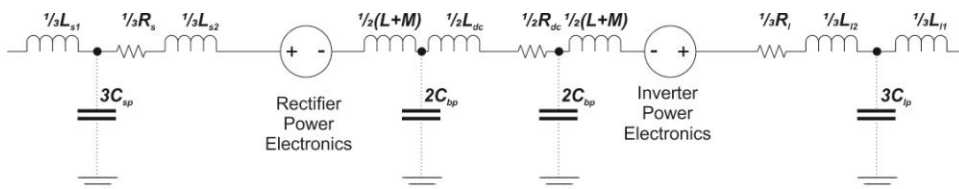
$$L \approx M$$

$$v_1 = L \frac{di_1}{dt} + M \frac{di_2}{dt}$$

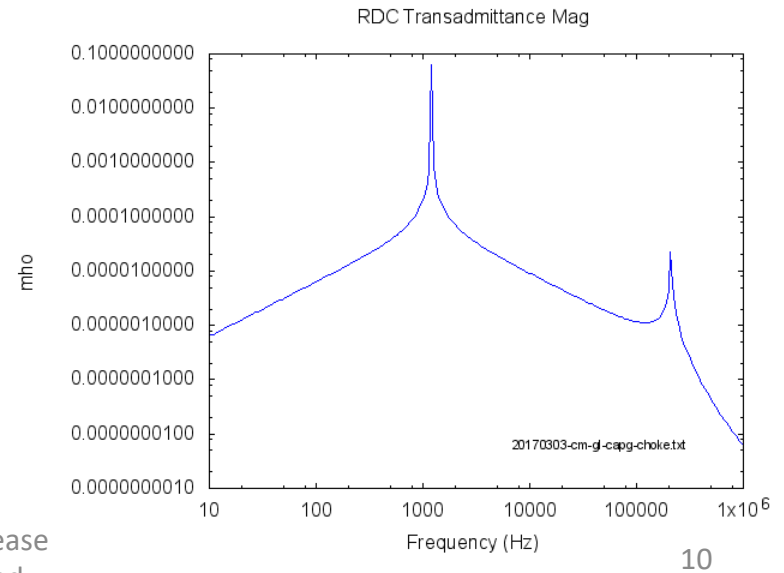
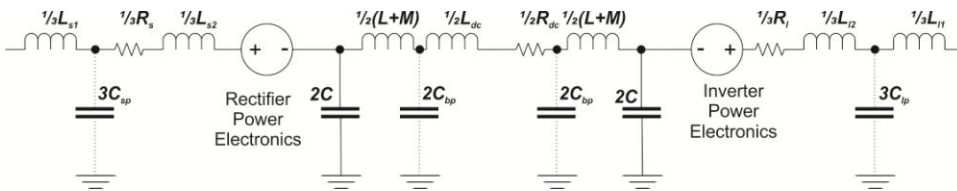
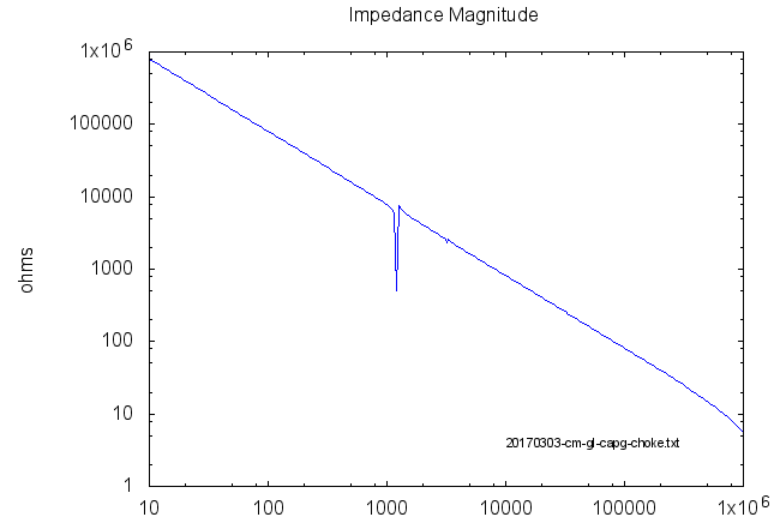
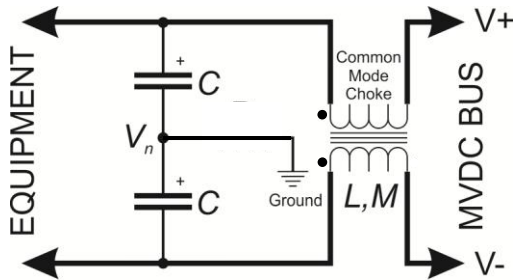
$$v_2 = L \frac{di_2}{dt} + M \frac{di_1}{dt}$$

$$i_{1cm} = i_{2cm}$$

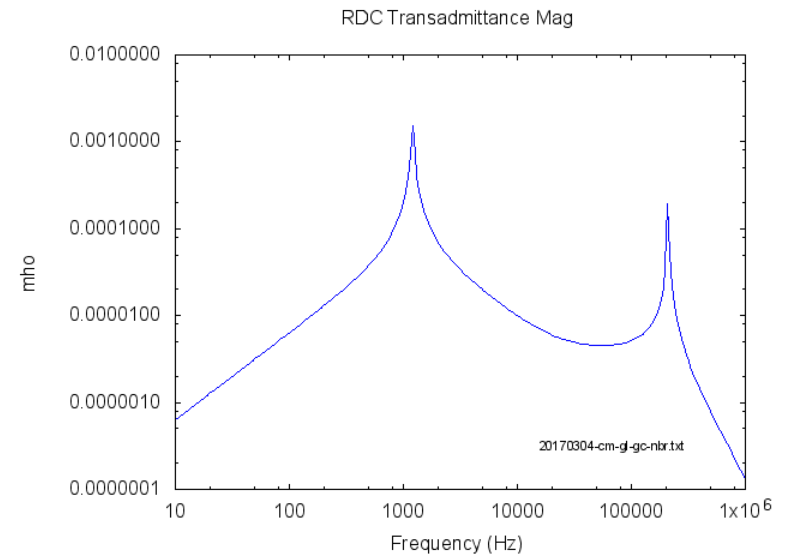
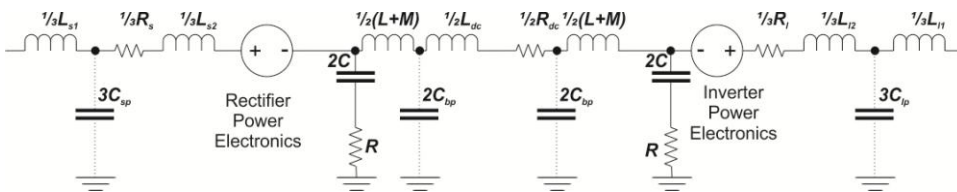
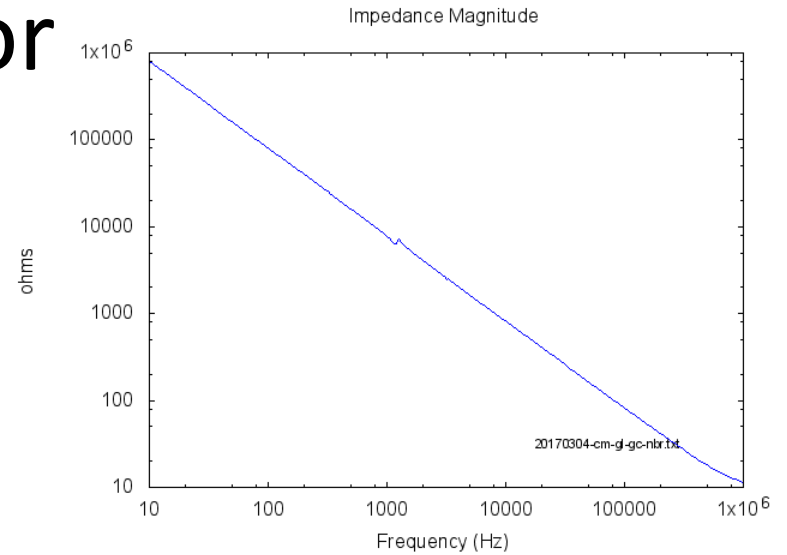
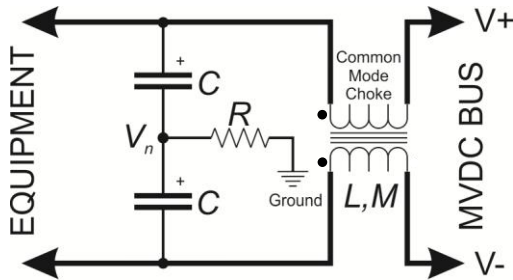
$$i_{1dm} = -i_{2dm}$$



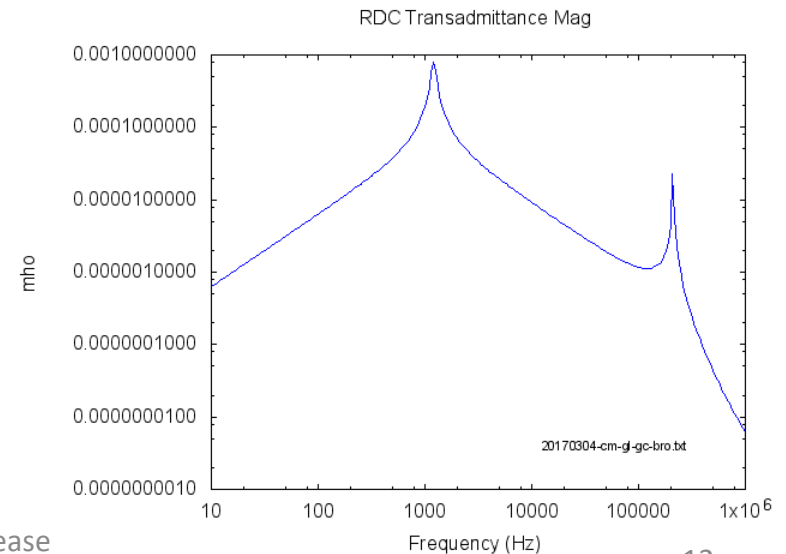
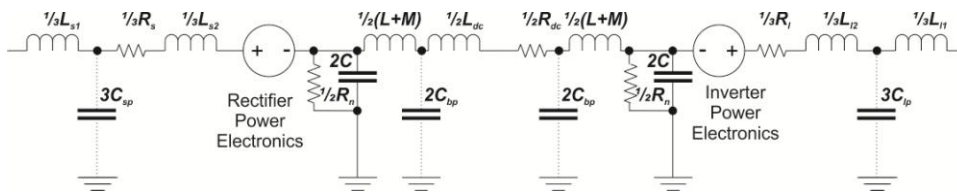
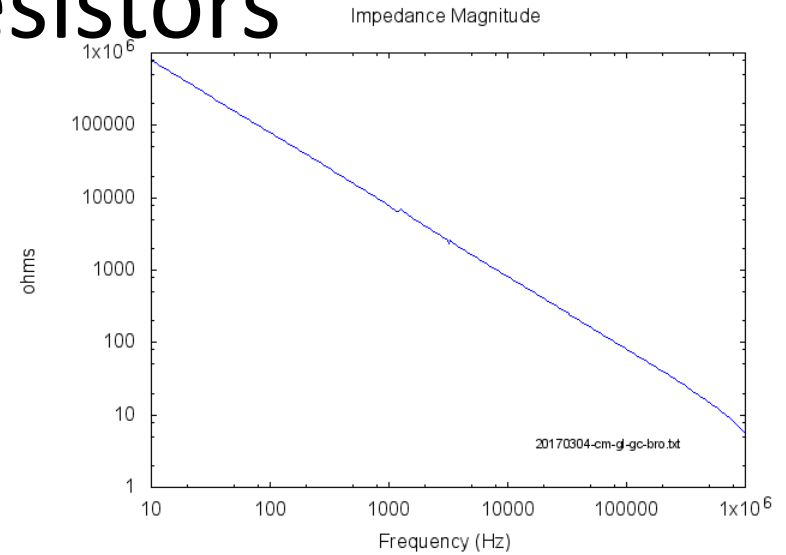
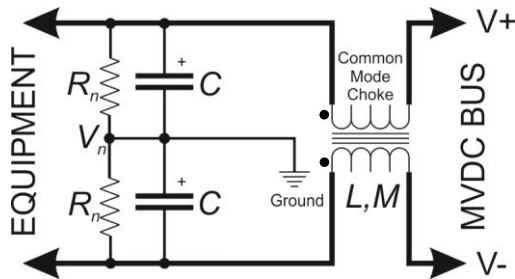
# Choke and Shunt Capacitors



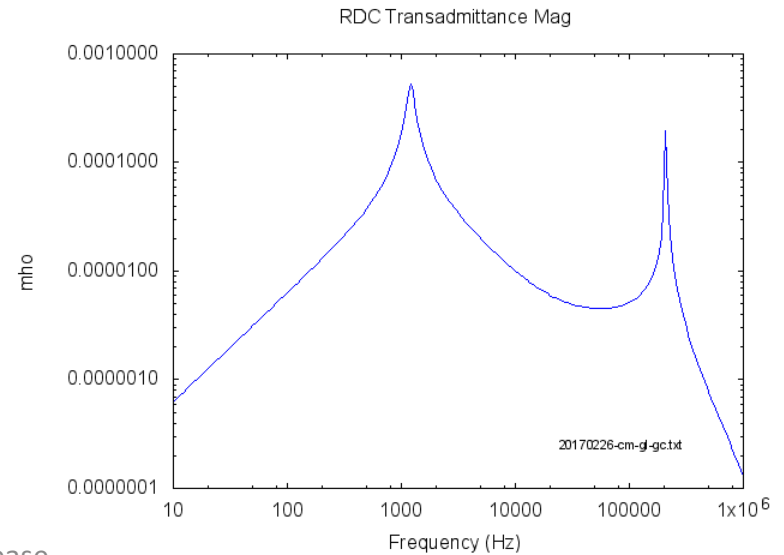
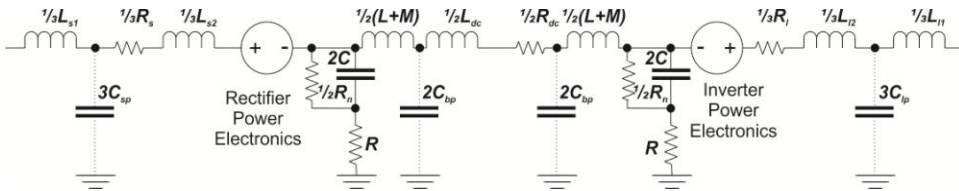
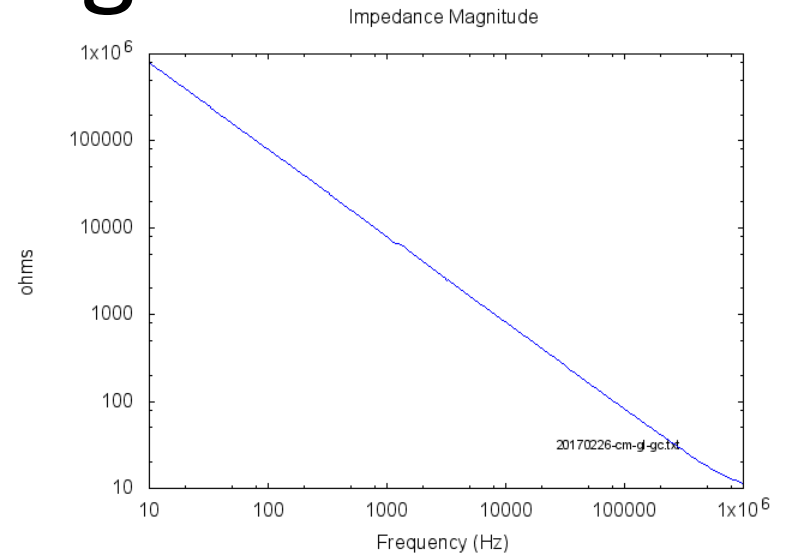
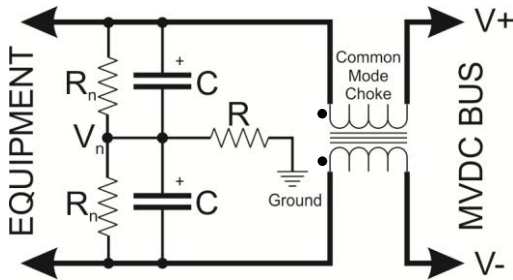
# Choke, Shunt Capacitors, and Damping Resistor



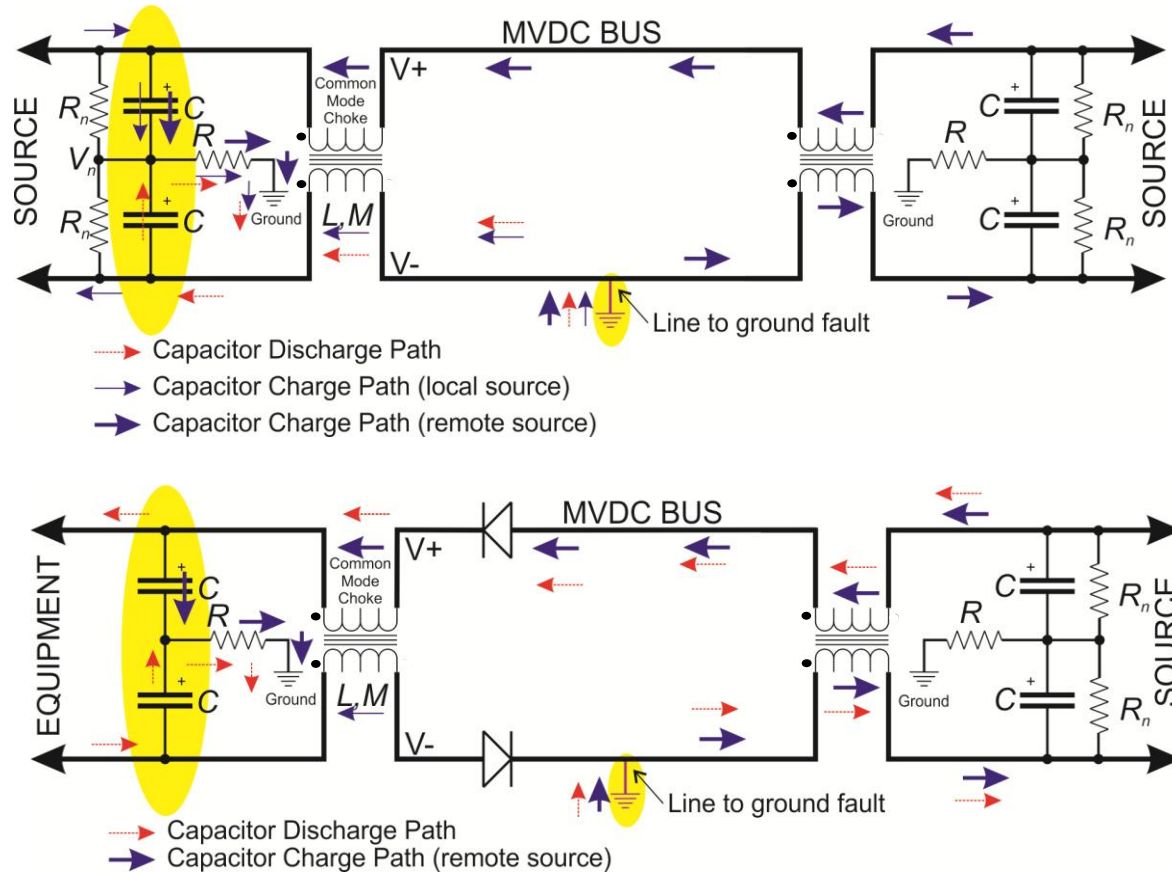
# Choke, Shunt Capacitors, and Balancing Resistors



# Everything

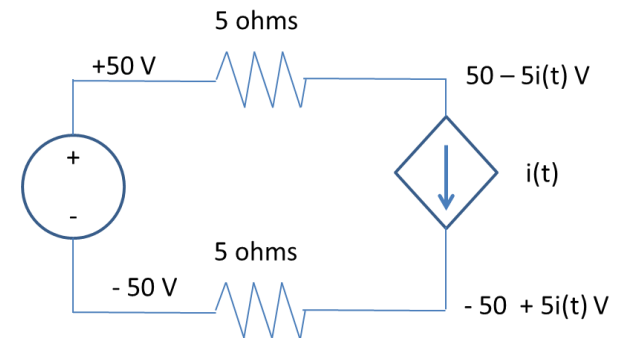
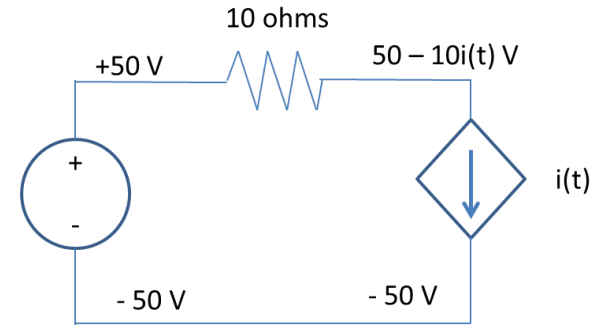


# Impact of Line to Ground Fault on Common Mode Current



# Reduce Common Mode Voltage

- Provide Symmetry
- Design power electronic gating algorithms to minimize common mode voltages
- Design rotating machines and associated power electronics synergistically to minimize common mode voltages
  - Consider two 3-phase systems 180 electrical degrees apart
  - Independently drive windings



# Summary

- Control of Common Mode Currents must be accomplished both at the total system level and at the module level.
- Need to develop common mode models
- Common mode impedance and transadmittance are good metrics to help characterize common mode performance
- Need to consider impact of ground faults
- Need to consider methods of reducing common mode voltages